



### Algorithm to Extract the Shortest Linear Edge and the Longest Diagonal of Single Isolated Human Insulin Crystals for In-Situ Microscopy

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CCE 2015, Mexico City, Mexico, October 28-30 2015



# Overview

- Introduction
- Algorithm
- Experimental results
- Summary





#### In-situ microscope

On-line automatic cell density estimation with no risk of culture contamination





## Introduction



Use of the in-situ microscope for on-line monitoring of human insulin crystallization processes

Images of first experiments show:

Homogeneous background 4 different classes of foreground regions  $C_n$ , n=0,...3: single crystals  $(C_0)$ , crystal clusters  $(C_1)$ , amorphous substance  $(C_2)$  and mixed regions  $(C_3)$ 



Human insulin crystal image





#### **Problem statement:**

Knowledge of the crystal size distribution at any time during a crystallization process is very useful to control the crystal growth, which in turn is very important, for example, to maximize the effectiveness of the insulin diabetes treatment

### **Challenge:**

Development of an algorithm to measure the crystal size distribution from the images capture by an in-situ microscope







## Introduction

### Approach

- 1. Development of an algorithm to measure the shortest linear edge and the longest diagonal of the single crystals
- 2. Use the developed algorithm to monitor these lengths during the crystallization process
- 3. Inference of the crystal size distribution from the length readings

Here the algorithm to measure the above mention lengths is presented only (it consists of seven modules)







### **Foreground segmentation**

1. Capture an intensity image I



Intensity image I





### **Foreground segmentation**

2) Estimate the local intensity variance at each pixel position



Variance image V





### **Foreground segmentation**

3) Threshold the variance image V

 $V_i > th$  : foreground (white)  $V_i \le th$  : background (black) where th=m<sub>1</sub>+4 $\sigma_1$ 

- $\sigma_1$ : standard deviation of the variance values at the background
- m<sub>1</sub>: mean of the variance values at the background



Thresholded image V<sub>th</sub>





### **Foreground segmentation**

4) Eliminate isolated white pixels by applying a 5x5 median filter







### **Foreground segmentation**

5) Eliminate any white region touching any image border







### **Foreground segmentation**

6) Eliminate white regions whose image area is less than 0.09% of the total image area







### **Foreground segmentation**

7) Eliminate black holes inside white regions

The remaining white regions represent the segmented foreground regions  $F_s$ , s=0, ...,S-1



Segmented foreground regions  $F_s$ , s=0, 1, 2 13





# Detection of single crystal regions

1) Compute for each segmented foreground region  $F_s$  a 7dimensional vector of rotation, translation and scale invariant shape characteristics  $C_s(k)$ , k=0, ..., 6, according to M.-K. Hu







# Detection of single crystal regions

2) Detect an arbitrary segmented foreground region  $F_s$  as the region of a single crystal if its shape vector  $C_s$  is much closer to the shape vector prototype  $P_0$  of the single crystals than to the shape vector prototypes  $P_1$ ,  $P_2$  and  $P_3$  of the other classes of foreground regions

$$||C_s - P_0|| \le ||C_s - P_n||, \forall n = 0,...,3$$

where

$$\|C_{s} - P_{n}\| = \sqrt{\sum_{k=0}^{6} (P_{n}(k) - C_{s}(k))^{2}}$$

The shape vector prototypes are computed a priori from a training set of images



Detected single crystals





# Improvement of contour accuracy

 Move each region contour point along the line segment, which goes from the region contour point to the region center of gravity, to that image position a, where the weighted sum of the intensity value and the values of the first and the second region contour derivatives becomes minimal



Detected single crystals with improved contour accuracy





### **Extraction of crystal lines**

 Extract the 6 lines that go through the 6 linear edges of each segmented single isolated crystal region by applying the Hough transformation to the region contour



Extracted 6 lines (in white)





### **Extraction of crystal vertices**

- Compute all the intersection points between all previously found 6 lines for each segmented single isolated crystal
- Select those intersection points which lie inside the segmented single isolated crystal region as the 6 crystal vertices



Found crystal vertices (in black)



# Finding the shortest linear edge

 Find the shortest crystal linear edge of each segmented single isolated crystal region as the segment between the found vertex positions whose length represents the minimal relative distance between all found vertices



Found shortest crystal linear edges (in white)



# Finding the longest crystal diagonal

 Select as the longest crystal diagonal of each segmented single isolated crystal region that line segment between the found vertex positions with maximal relative distance between all found vertices



Found longest diagonals (in white)



## **Experimental Results**



- Implemented in C under Windows XP
- Tested with 60 real images
- Intel Core Duo CPU at 2.2 GHz and 2 GB RAM
- Average processing time of 1 sec/image
- Absolut length error in the extracted shortest linear edges was in average 4.18%
- Absolut length error in the extracted longest diagonals was in average 2.32%



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# **Experimental Results**



Extracted shortest linear edge for test image 35 Extracted longest crystal diagonal for test image 35





## **Experimental Results**



Extracted shortest linear edge for test image 44

Extracted longest crystal diagonal for test image 44



## Summary



- An algorithm was presented which is able to extract the shortest linear edge and the longest diagonal of each single crystal found in an image captured by an in-situ microscope
- In average, the lengths are delivered 1 second after the image is captured with an accuracy of 4.18% and 2.32%, respectively





# Thank you!



#### Image Processing and Computer Vision Research Lab (IPCV-LAB)

Universidad de Costa Rica



Computer Vision for Autonomous Robotics Biomedical Imaging





## Thank you again!





# **Contact Information**

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